THE MODEL U-300 UTILISCOPE

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SECTION I

IMPRODUCTION

The Model U-300 Utiliacope has been designed to replace the Model U-200 Utiliacope. In operation, both sales-wise and circuit-wise, the U-200 was found to have several imadequacies. The design of the U-300 was undertaken to everage these imadequacies which the field operations and sales impostigation into new uses of industrial television provided.

Ecoso of the main chericomings of the U-200 Utiliscope are as follows:

- I. Magarepol aspect zatio
- 2. Too much "5" distortion
- 3. Insufficient definition
- A. Brauffloient video gain
- 5. Resign of fast lanses impossible due to long focal length required by solid cathode Dissector
- 6. Empropor "packaging" of units
- 7. Failure of lew voltage rectifiers
- f. Enter-reaction of field frequency control and linearity controls
- 9. Monitor line structure too coarse
- 10. Equipment too costly to manufacture
- H. Equipment should be simplified in spite of improved performance specializations
- 12. Transformer tapped primary method of compensating for line voltage unsatisfactory
- 13. Objectional fold-over on right hand side of picture

The above deficiencies have all been overcome on the Model U-300 and should be construed as improvements over the Model U-200. Figures 2 and 2 show pictures taken from the Monitor cathode ray tube.

SECTION II

GEWERAL

The Model U-300 Utiliscope is a wired television equipment designed to be used wherever the application requires remote viewing of an elejant or objects.

Appendix No. 1, attached to this report, sets forth the openificables of the Model U-300. Figure 3 shows the complete equipment which includes, for the sending end, a Gamera Unit and a Power Unit, and for the receiving and a Monitor Unit.

Simplicity of design and freedom from service are considerablence of sujer importance. Since field difficulties are directly properblemate to the number of tubes in an equipment, a minimum number of tubes have been used in order to meet the performance specifications. A total of fifteen tubes, exclusive of the cathode ray tube and Dissector, are used. These fifteen tubes are all of the common receiving type.

Referring to Figure 3, the Camera Unit is placed near the object to be wiswed.

This unit is connected through a single multiple conductor cable to the Power

Unit. These units may be separated by as much as twenty-flive feat.

This sending end is then coupled by three coardal cables to the Homiter which may be separated by a distance of one thousand fact or long.

These three cables transmit the video, herizontal syme pulses from the sending end to the Monitor.

Since simplicity of operation and freedom from service are of entrance inportance with this type equipment, it is felt that the use of three cables, rather than one cable which would carry a composite signal, is vell justified.

which is a block diagram of the complete equipment. The image is focused optically on the cethods of the Dissector, V201. Herisontel, wartist following tion power, focus power and the multiplier voltage is supplied to the Dissector from the Power Unit. The video signal from the Dissector sollower in to the automatic black level setter, V2034. Electrical pulses are also fed to V2034from the Power Unit. The composite signal is then applicately 1203 after which it goes through V2035which matches the composite output to the

Referring to the Power Unit, VIOL supplies verticed doffection power to the Cemera Unit as well as vertical symo pulses for the Comiter and vertical blanking pulses which feed VIO2. VIO3, the beam relaxor, supplies herisental chanking pulses herisental chanking pulses to vIO2. VIO2 mixes, clips and shapes the horizontal and vertical blanking pulses. The beam relaxor, VIO3, also supplies horizontal symo pulses to the Monitor. VIO6 is a cathode follower which isolates the vertical blanking pulses from the symo pulses fed to the Monitor. The beam relaxor

furnishes high voltage pulses which are rectified by V104 and V105, which are in parallel. These rectifiers supply the multiplier and cathode voltage to the Dissector.

Finally refer to the Monitor. The vertical sync pulses trigger V301 which supplies vertical deflection power to the cathode ray tube. The horizontal pulses, from the Power Unit, are amplified by V304 which synchronizes the beam relaxor V305. This beam relaxor supplies horizontal deflection to the Dissector tube as well as high voltage pulses to V306 and V307. These two rectifiers supply approximately 7.5 NV to the picture tube anode. The video signal from the Camera, is amplified by V302 and V303 before being applied to the grid of the picture tube. A 1834 is used as the D3 restorer,

The U-300 has a standard four to three aspect ratio. The resolution of the system is 300 lines horizontally and vertically.

SECTION III

METHOD OF OPERATION

This section will cover the operation of the various circuits in detail.

Figure 5 is a schematic of the Camera; Figure 6 is a schematic of the Power Unit and Figure 7 the Monitor.

1. Camera

The Camera consists of five main units as follows:

- 1.1 Lens
- 1.2 Dissector
- 1.3 Dissector Coll System
- 1.4 Video Amplifier Unit
- 1.5 Main Chassis

1.1 Lens

The lens focuses the object on the translucent cathods of the Discotor.

This lens is a Miller Optical Co. Model ULS with a 90 kM focal length and a speed of Fl.4 or better. The lens is coated for 70004° transmission.

The mounting uses a rack gear and pinion type focus adjustment. The angle of coverage for a 2" horizontal scan is approximately 27°. The optical focus adjustment will fecus on objects between 20" from the lens and through infinity.

A remote control motor can be attached to the planton gear for remotely focusing the camera.

1.2 Dissector

The Dissector is new in that it uses a translucent eathede instead of the solid cathode as previously used. Figure 3 shows a photograph of the Dissector which is a DSOL type. Figure 9 shows a typical response curve of this type Dissector. The peak sensitivity is in the near infra red pertion of the spectrum.

The cathode connection is brought out to a cap, which is painted yellow, on the front of the tube. Directly behind the cathode can be seen five

rings. Each ring is brought out through a terminal on the front of the tube. Immediately behind the five rings is the nickel wall coating on the anodo. There is an overall voltage between cathode and anodo of approximately 400 volts. These rings are connected between the cathode and anode and have a differential of 75 volts between them. The purpose of these rings is to improve the field in the vicinity of the cathode and decrease the amount of "S" distortion.

There is one more cap on the front of the tube which is painted red. This connection is not used in the equipment as it is used only during the formation of the Dissector.

An eleven-stage multiplier is mounted at the rear of the tube. The aperture, which in most cases is a 30 mil square, is located at the front of the multiplier isplier housing. This multiplier is of the A_g - M_g type. This type multiplier is used instead of the C_g - 0 - A_g in order to provide better uniformity in multiplier performance from tube to tube. The problem of casesium shorts in the multiplier is also eliminated.

The above photo sensitivity is approximately 20 ma per lumen. There is approximately 6 x 10⁻¹⁰ amperes entering the square 30 mil aperture at any instant when the illumination is seven foot candles on the cathode. This current is multiplied by approximately 500,000 by the electron multiplier which has approximately 200 volts across each stage.

1.3 Dissector Coil System

Figure 10 is a photograph of the dissector coil assembly. This assembly

contains the horizontal deflection coil, vertical deflection coil and focus coil. The features of this coil assembly are listed below.

- 1. Complete plug-in assembly
- 2. Minimum "S" distortion with simple construction
- 3. Horizontal inductance 2 mh; horizontal resistance 8.9 ohms
- 4. Vertical inductance 2.5 uh; vertical resistance 1 chm
- 5. Focus coil turns 2,900; focus soil resistance 210 chas
- 6. Electron image magnification approximately 1.5

Referring to Figure 10, the horizontal coil is the inner coil and is approximately nine inches long. The vertical coil is a toroidal type approximately one inch long wound over an iron form. This coil fits smugly on the horizontal coil and is directly behind the focus coil. These two coils are rotated 90°, electrically, with respect to each other. The focus coil is semi-layer wound and sets directly over the dissector cathode in the coil assembly housing. The coil assembly is supported by three stude on the front of the focus coil. These three stude extend through slots in the baltelite front plate of the coil housing and are secured with thumb rate. The coil assembly can be rotated through the range of these slote to align the picture electrically with the picture on the Dissector cathode.

1.4 Video Amplifier Unit

Figure 11 shows a bottom view of the video unit and Figure 12 shows a schematic of this unit. This unit is connected by three plugs and can be removed readily without the use of a soldering iron. The function of this unit is to mix the blanking pulses with the video from the Dissector collector, providing an automatic black level setting, amplify the composite signal and match the

output to a 93 ohm line.

Referring to Figure 12, V203A is the automatic black level setter. The operation of this tube is as follows. Relatively large blanking signals are fed to the cathode of V203A in series with the video from the Dissector collector. This video is developed across R231 which is the Dissector collector load.

The DC voltage developed across the Dissector collector load recistor due to random noise in the Dissector will remain a constant value. Any light which strikes the Dissector cathode will cause a corresponding increase in collector current, hence increased negative voltage of the collector.

Since more light causes more electrons to flow to the collector, the collector becomes more negative with respect to ground.

The initial clipping level of the black level setter can be properly adjusted by applying just enough positive voltage to the cathode of V_V to allow only a very small amount of the blanking pulses to come through V203A. This is accomplished by varying R234 to give the proper potential. R233 is an isolating resistor to minimize the capacitance across the collector load.

Any light on the Dissector cathode will then cause more negative voltage to appear at the clipper cathode, which will pass through the clode, so the pedestal will always be full but no video can ever extend beyond the black level. This tube has a loss of approximately 6 db.

Again referring to Figure 12, V202 is used as the video amplifier and has a gain of approximately 18. R224 has been made large to minimize "bounce" due to line surges. Decreasing the value of this resistor will increase the gain, however if this is done picture "bounce" due to line surges becomes objectionable. R226 and C205B are used to minimize video "bounce" due to sudden line surges.

V203B is used as a cathode follower to provide a low impedance output for the video line. R222 and R230 have been designed to give maximum linear output without exceeding the tube rating. The gain of this tube, with the line properly terminated, is approximately .3. Figure 13 gives the overall frequency response curve of the video unit.

1.5 Main Chapsis

Figure 5, the Camera schematic. IZO4 is the socket into which the coil system is plugged. P2O5 plugs into the video unit. The Disasctor multiplier voltage divider is shown in the upper loft-hand portion of the schematic. The overall voltage across the multiplier is approximately 2000 volts, or 180 volts per stage. G2O6 and G2O7 are necessary to improve the low frequency response of the multiplier due to the high impedance of the multiplier divider. Without these capacitors, a scone which has a very black square against a white background will be followed by trailers. R2O2 is the width control. Actually this width control is an overall size control in that it changes the cathode-anode voltage. An increase in this voltage will decrease the width of the scanned image and also the height of the image.

R208 is the video overload control. Actually this controls the gain of the multiplier. It is necessary due to variation in Dissector tubes and extreme light conditions which may be encountered. For example, when the control is at the center of its range, the gain of the multiplier will be at maximum. It will be necessary to operate the multiplier at the maximum gain when the light level is quite low and the picture is very noisy. However, if the light is high, it will be necessary to reduce the gain of the multiplier with this control. If this is not done the last steges of the multiplier will be operating in an overload condition. Since this overload problem concerns only the last two or three multiplier stages, the control is used on stage #6.

Figure 14 shows the saturation a little more clearly. Referring to the figure, the x coordinate shows the light on the photosensitive cathodo while the y coordinate shows the collector current for varying amounts of light. Curve A is a plot of the cathode current as it varies with light. If there is no multiplier saturation, the collector current should follow the same characteristics as this curve. Curve G illustrates the saturation of the multiplier when using 200 volts per stage on this particular Dissector. It will be noted that saturation occurs at a variac setting of approximately 30 volts. Curve B shows the collector current curve for the case when the gain of stage #6 has been considerably reduced by dropping the voltage between multiplier stage #5 and #6. It will be noted also that this curve is relatively linear up to the maximum variac setting. Incidentally, the variac voltage shown is the voltage which was supplied to a small slide projector. The light from this projector was then projected on the cathode of the Dissector, Referring again

to the curve, it can be seen that if the light on the cathode varied between 50 and 100, the actual collector current change would be only about .3 ma. However, with the gain decreased in stage #6, the collector current change would be approximately 1.2 ma, or four times the video cutput. If the light were to swing between the values of approximately 20 and 30 or 90, it can readily be seen that the points which correspond to maximum light on the cathode would be crushed and the picture would have a washed-out appearance.

If this multiplier is operating in the overload condition, the automatic black level setter will not operate properly. The best way to determine the setting of the video overload control is with an oscilloscope at the Camera video output. The gain of the multiplier can be increased to a point just before the video is distorted. If no oscilloscope is available, the Monitor contrast control should be set between a and a maximum contrast. The Camera video overload control should then be adjusted for the best picture.

R232 is the electrical focus control. It is important that this focus control be set correctly. If it is not properly set the picture detail will be down and the picture may exhibit "S" distortion.

This focus control must always be adjusted after each change of either the width control or the video overload control.

2. Power Unit

Figure 15 shows a photograph of the Power Unit with the case removed. The function of the Power Unit is to deliver heater voltage, B voltage, multiplier

voltage, scanning power and blanking signals to the Gamers Unit. This is done through a single multi-conductor cable. The Power Unit also supplies vertical sync pulses and horizontal sync pulses to the Monitor.

The Power Unit draws approximately 100 watts and will operate on a line voltage of between 95 volts and 135 volts. A mater is swailable on the front panel to determine the proper voltage control setting for any voltage between these two limits. The mater is provided with a red line and the voltage control, which is available from the front, is adjusted such that the meter pointer coincides with the red line.

Figure 6 shows a schematic of the Power Unit. An analysis of the various circuits in the Power Unit will be made under the following sections.

- 2.1 Power Supply
- 2.2 Horizontal deflection and high voltage supply
- 2.3 Vertical deflection circuit
- 2.4 Hanking miner and sync output

2.1 Power Supply

The nominal power supply voltage is 275 volts after filtering. The ripple voltage after filtering is .7 volts RMS. A bridge rectifier circuit is used which utilizes eight 200 mil selenium rectifiers. The selenium rectifiers and bridge circuit were chosen for their ability to give trouble free operation for extremely long periods of time.

A variable series resistor is used between the rectifiers output and the filter to permit proper voltage adjustment under wide limits of input line voltage.

A heavy duty power transformer is used. This transformer is conservatively rated at 200 mils although approximately 160 mils is the total current drained. This transformer also supplies heater voltage for the tubes on the Power Unit and Camera. A 4 amp fuse is used in ceries with the primary of the transformer. A 110 volt mean pilot bulb is also used. The mean bulb was chosen for its long life.

2.2 Horizontal Deflection and High Voltage Supply

A single 616 in a beam relawor circuit is used to provide horizontal scanning power for the Camera as well as to supply high veltage pulses to the multiplier voltage supply rectifiers. The beam relawor is a self oscillating circuit chosen for its durability and high efficiency. This is a free running oscillator which operates at a frequency of approximately 21.5 kg. The beam relawor has a high degree of frequency stability over long periods of time. This frequency is controlled by the adjustable cathode resistor R120. The correct setting of this resistor is approximately 75 ohms. This resistor should never be reduced below 25 chms as this will cause improper operation of the blanking miner since this cathode pulse is used to feed the horizontal blanking to the blanking miner. This control is not critical and will vary slightly from transformer to transformer. It should never be necessary to adjust this resistor unless the transformer has been replaced.

Figure 16 shows a close-up of the horizontal deflection transformer. This transformer consists of a grid winding of approximately 100 turns. The plate winding which consists of 500 turns is wound directly over the grid winding. The high voltage winding consists of 300 turns connected in auto

transformer fashion. Considerable development time was spont on this transformer in that it must serve three functions and these functions are interdependent. The transformer must provide the proper scanning power to the Camera, the proper high voltage for the Dissector multiplier, and its return time must be slightly faster than the blanking return time. These criterions must be not with satisfactory scanning linearity. The return time of this transformer is 5.7 micro seconds or .12 H. This transformer has been tested at three times its normal operating voltage with no evidence of corons or breakdown. Rlo8 is used as a damping resistor to remove the overshoot which would otherwise occur through the scanning colls causing severe non-linearity.

The positive impulse derived from the horizontal deflection transformer is rectified by the two IBBs in parallel. This provides a negative voltage of approximately 2500 volts. Since the current drain very nearly approaches the current rating of the IBB, two are used in parallel. This is done as an added precaution against failure in the field.

2.3 Vertical Deflection Circuit

The vertical deflection circuit which consists of the dual triode VIOI, must supply vertical deflection power to the Camera, vertical blanking pulses to the blanking mixer and vertical sync pulses to the Honitor.

One-half of the 6SN7, VIOI, is used as a blocking oscillator. The frequency determining time constant is GIOA and RIOA. The lower end of the blocking oscillator transformer is returned to the 6.3 volt heater winding on the power transformer. The capacitor CIO5 on the plate of the vertical oscillator as well as the shielding of leads to the height pot-

entiometer are necessary to remove horizontal pickup which occurs during the retrace of the beam relaxor. This pickup will cause "jitter" or a "bounce" in the scanning amplitude. A resistor, R105, is inserted in the cathode circuit of the vertical oscillator. A positive pulse is developed across this resistor which is used for blanking and Monitor synchronization. C106 reduces the horizontal pickup on this lead. The second section of V101 is used as a conventional vertical amplifier. R118 is the vertical linearity control while R119 is the height control. T102 is the vertical output transformer used to present the proper plate lead impedance on the vertical amplifier from the vertical scanning coils.

2.4 Blanking Mixor and Sync Output

Referring once again to Figure 6, V102 is the blanking mixer. One section of this tube is used to mix the horizontal and vertical blanking pulses while the other section is used as a cathode follower. A positive vertical pulse is fed to the cathode of the blanking mixer. A negative horizontal pulse from the beam relaxor cathode is injected on the grid of the blanking mixer. A very low plate voltage is used, hence the blanking pulses cause very early plate saturation of the tube. This causes the base line of the blanking pulses to be absolutely flat which is extremely important, otherwise at low light levels a shading component will appear. The values of R109 and R112 were picked very carefully to provide proper phasing of the horizontal blanking pulse with respect to the initial sync pulse delivered to the Monitor.

V106 is a cathode follower to isolate the cathode of the vertical oscillator from the Monitor vertical oscillator. If this is not done a large pulse is

fed back to the Power Unit from the Monitor vertical oscillator. This pulse, if applied across the cathode resistor of the Power Unit vertical oscillator is slightly out of phase with the cathode pulse and will make it impossible to derive a clean vertical blanking pulse from this point.

3. Monitor

The Monitor is quite conventional and will not be treated in too much detail. The Monitor will be broken down under the following headings:

- 3.1 General
- 3.2 Horizontal Deflection and High Voltage System
- 3.3 Vertical Deflection System
- 3.4 Symc Systam
- 3.5 Power Supply
- 3.6 Video Amplifier

3.1 General

Honitor is so constructed that the cathode ray tube and all other tubes may be shipped in place. A small clamp is used to keep the 616 tube in its socket. Figure 18 shows a bettem view of the Menitor. All controls are available from the front. Brilliance, contrast and focus controls are available screwdriver adjustments. Other controls are available behind a hinged door. A meter is used to properly set the width control for any given line voltage between 105 and 135 volts. This meter can be seen when the door on the front panel is open. This meter has a green shaded area on its face. The width control should be set to just completely fill the mask. If the equipment is functioning properly, with

the correct amount of horizontal scan, the mater pointer should be within the green area.

A plug termination for the video input cable is provided at the rear of the Monitor. This terminating resistor is 120 ohms for all normal installations. However, where more than one Monitor is used, this plug termination should be changed to properly terminate the video line.

3.2 Horizontal Deflection and High Voltage System

A 616, V305 is used in a beam relaxor circuit to provide horizontal defiection and high voltage for the picture tube. Circuit-wise this is quite similar to the beam relaxor on the Power Unit. However, synchronization is controlled by injecting the horizontal sync pulse from the Power Unit on the screen of the 616 and controlling the frequency by means of a variable cathode registor. Care should be taken in the initial adjustment of the horizontal frequency control. The beam relapor will remain in sync over a rather large range of the frequency control. As this control approaches one and of its "look-in" range the ploture width will decrease. The proper setting of this control is near the other end of its "look-in" range. The controls on the Monitor are not too critical, however after an equipment is set up in proper fashion, the line voltage should be varied over approximately a 20 volt range with a variac to make sure the Monitor will remain in synchronization. If it does not, a slight re-adjustment of the horizontal sync control should be made to make sure the Monitor will remain in sync over at least this range.

Besically the beam relexor transformer T303 is similar to the Power Unit

beam relaxor transformer with the addition of two heater windings for the 183 rectifiers. The transformer is designed to match a 2 MM deflection yoke. The transformer is also designed to provide 7500 volts for the picture tube and the return time must be faster than the Camera blanking time. This return time is 5.7 micro seconds or .12 M.

Two 183 tubes are used in a voltage doubler circuit to provide the picture tube high voltage. The voltage doubler circuit was chosen as providing a more efficient overall circuit where power drain and return time are of great importance.

3.3 Vertical Deflection System

The vertical deflection system is very similar to the Camera vertical deflection system. C303 and R305 are the frequency determining elements.

These fixed elements have been chosen as tests have shown the oscillator will stay in sync over large variations of line voltage and other parameters.

3.4 Syno System

The vertical sync from the Power Unit is injected directly into the vertical oscillator.

The horizontal sync is amplified and injected by both sections of V304. The grid, cathode and plate time constants were carefully chosen for the horizontal sync amplifier to properly phase the triggering of the beam relaxor with respect to the blanking pulse.

3.5 Power Supply

The power supply is also very similar to the supply used on the Power Unit except the DC output through the filter is 350 volts. The ripple voltage appearing at this point is .6 volts RMS.

3.6 Video Amplifier

A two-stage video amplifier is used. V302 is a type 5693. This tube is the same as the 6637 except that it is of the ruggedized long life type. This tube is relatively free from microphonics. A 6AC7 is used as the second video amplifier. R314, R316 and C306 are used to reduce "bounce" due to line surge. Figure 19 shows the overall response curve of the Monitor video system.

A 1N34 is used as a partial DC restorer. The function of the 1N34 is to maintain the average brilliance level constant on the kinescope during rapid changes of scene which are encountered when the Utiliscope is used to view rapidly moving objects. It is also helpful in reducing "bounce" due to sudden line voltage surges.

SECTION IV

MISCELLANEOUS

1. Wave Shapes

Appendix 2 attached to this report presents the wave shapes which should be obtained at various points of the circuit. These wave shapes correspond to the points on the schematic diagram as marked. For example, (F2) shows a

wave shape of a point on the Power Unit. Referring to the Power Unit schematic, the point P? can readily be seen. These wave shapes were taken with a Dumont Type 241 Oscilloscope. The wave shapes shown were taken with the equipment in normal operating condition while viewing an average scene.

2. Voltage Measurements

DC voltage measurements are shown on the three schematic diagrams. These voltage measurements were taken with a Simpson Model 260, 20,000 chm per volt meter. Voltages were taken under normal operating conditions.

3. Caution

Considerable design effort has been expended on this equipment. It has been pointed out that many factors are interdependent. Should any trouble occur in the equipment, this trouble should be remedied by finding the source of the trouble and returning the equipment to its proper operating conditions. A trouble which develops should never be corrected by a redesign of any portion of the equipment as this can lead to other difficulties which may be more difficult to find. For example, an incorrect remedy of Monitor vertical syncronization might allow the vertical sync to work properly but blanking difficulties, either in blanking pulse amplitude or width might occur.

As an additional word of warning, no work should be done on the Camera Unit with the power turned on as there are many points which have potentials of greater than 2 KV on this unit.

General:

- 1. Number of Units (3)
 - 1.1 Camera Pickup
 - 1.2 Camera Power (Sending end)
 - 1.3 Monitor (Receiving end)
- 2. Maximum Separation Between Units
 - 2.1 Camera Pickup Unit to Camera Power Unit: 100 Feet
 - 2.2 Single 17 Conductor Interconnecting cable
 - 2.3 Sending and to Receiving end: 1000 Feet
 - 2.4 Three RG62U connecting cables
- 3. Operation Continuous or Intermittent
- 4. Maximum Ambient Temperature
 - 4.1 Camera Pickup and Camera Fower Unit: 65°C.
 - 4.2 Monitor: 50°C.
- 5. Lens
- 5.1 Miller Optical Company Fl.4 (coated) 90 MM Focal length
- 5.2 Focus Adjustment 20 inches through infinity
- 6. Illumination Required
 - 6.1 Minimum object illumination required, about 300 foot candles of sunlight, or 2870° Kelvin tungsten-lamp light.
- 7. Power Requirements
 - 7.1 Nominal 115 volt AC (60 cycle only)
 - 7.2 Camera Power, 100 Watts
 - 7.3 Monitor Power, 125 Watts
- 8. All Controls Available From the Front (except clipping level control)
- 9. Available Controls
 - 9.1 Camera Pickup Unit None
 - 9.2 Camera Power Unit None
 - 9.3 Monitor Unit Three
 - a. Focus
 - b. Brilliance
 - c. Contrast
 - 9.4 Monitor Remote Control of Camera Four
 - a. Lens Focus
 - b. Lens Shift
 - c. Magnetic Focus
 - d. Video Overload

10. Pre-set Controls

- 10.1 Camera Pickup Unit Two
 - a. Scan size (width)
 - b. Clipping Level
- 10.2 Camera Power Unit Four
 - a. Height
 - b. Vertical Linearity
 - c. Line V ltage
 - d. Horizontal Linearity
- 10.3 Monitor Six a. Width

 - b. Height
 - c. Vertical Linearity
 - d. Horizontal Centering
 - e. Vertical Centering
 - f. Horizontal Sync

11. Tube Complement - Total Seventeen

- 11.1 Camera Pickup Unit Three
 - a. Dissector One
 - b. Receiving Tubes Two
- 11.2 Camera Power Unit Six
 - a. Receiving Tubes Four
 - b. Rectifiers Two
- 11.3 Monitor- Eight
 - a. Cathode Ray Tube One
 - b. Receiving Tubes Five
 - c. Rectifiers Two

12. Accessable Plug Termination on Monitor for Video Line

13. Each Power Transformer is Fused

Electrical Specifications:

- Direct Horizontal & Vertical Synchronization of Monitor
- 2. Scanning Frequencies
 - 2.1 Horizontal 21,500 cycles (free running)
 - 2.2 Vertical 60 cycles synchronous with power line frequency
 - 2.3 Non-interlaced

- 3. Aspect-Ratio 4/3

 - 3.1 Monitor Picture Width 8-1/4"
 3.2 Scanned Image on Dissector 2 inches Wide Nominal; 1-7/8" minimum
- 4. Resolution (center of picture)
 - 4.1 Morizontal 300 lines
 - 4.2 Vertical 300 lines
- 5. Video Bandwidth 4MC
- 6. Video Gain

 - a. Camera 2 voltsb. Monitor 80 volts

From Dissector to Cathode-ray 160 volts

- 7. Maximum Overall Scanning Distortion
 - 7.1 Horizontal 15%

 - 7.2 Vertical 10% 7.3 "S" Distortion 10%
- 8. Design Center Line Voltage 115 volts
 - 8.1 Operating Line Voltage Center 105 volts to 130 volts
- 9. Picture Tube Anode Voltage: 7500 volts Nominal
- 10. Dissector Multiplier Voltage: 1900 volts Nominal

Mechanical

- 1. Size
- 1.1 Camera Pickup Unit 9 3/4" Wide x $8\frac{1}{2}$ " High x $17\frac{1}{2}$ " Deep 1.2 Camera Power Unit 9 3/4" Wide x $8\frac{1}{2}$ " High x $17\frac{1}{2}$ " Deep 1.3 Monitor 13" Wide x 16 5/8" High x 20 3/8" Deep

- 2. Weight
 - 2.1 Camera Pickup Unit 47 pounds
 - 2.2 Camera Power Unit 37 pounds
 - 2.3 Monitor Approximately 60 pounds

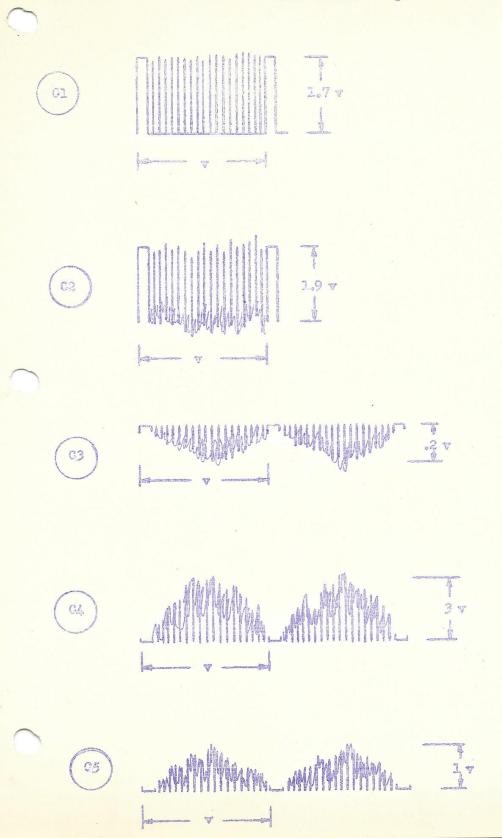
- 3. Mounting Provisions Shock Mounts
- 4. Line Power Input Plugs Locking Type
- 5. Appearance Rugged and Reliable but Cost a Major Consideration

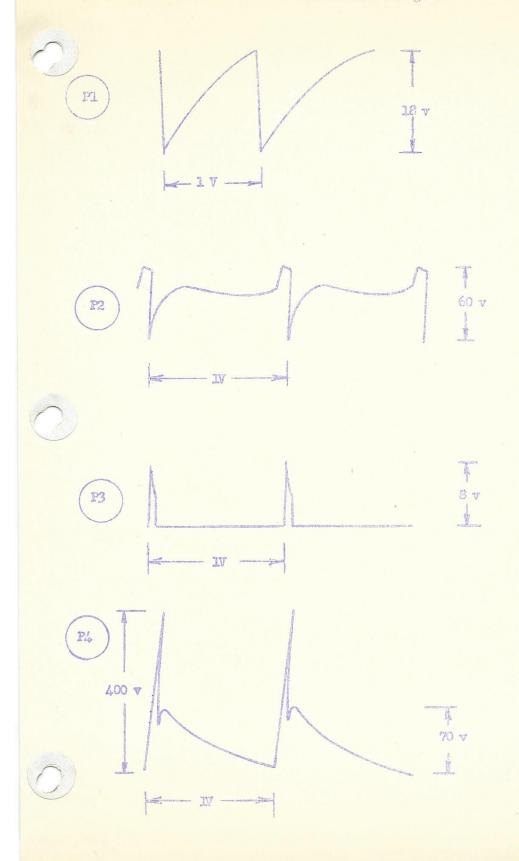
Pickup Tube - Translucent Dissector Type D30LL

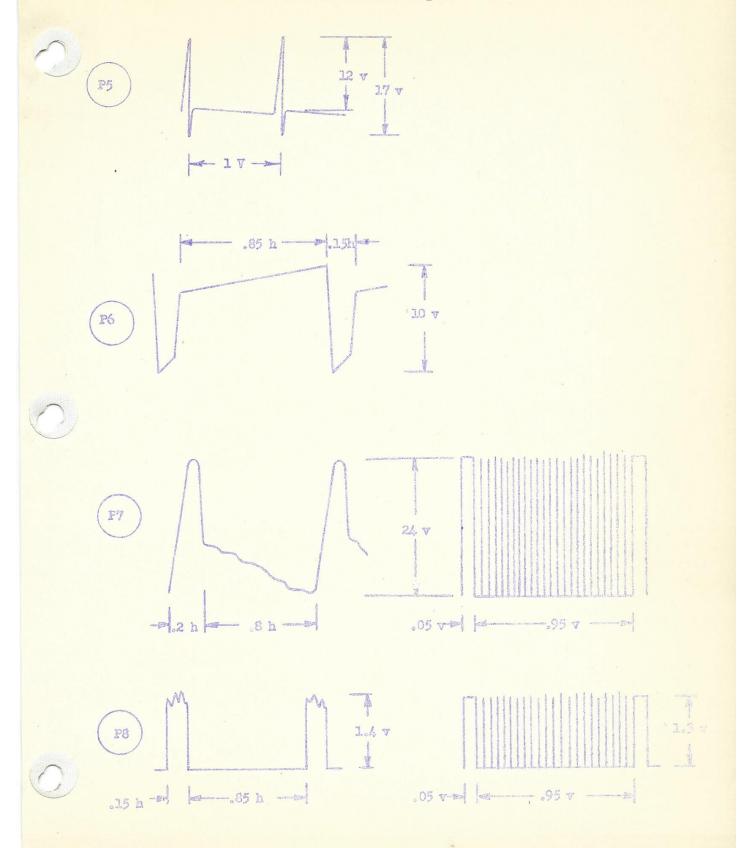
Miscellaneous

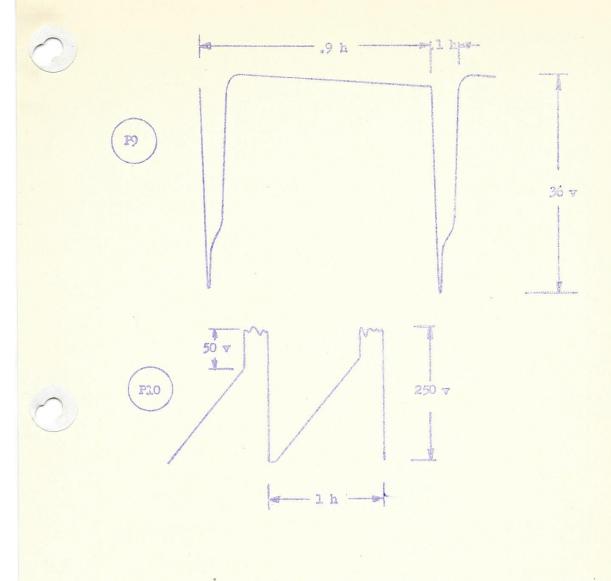
1. Picture Tube - Type 10FP4 (aluminized)

WAVE SHAPES - Page 1

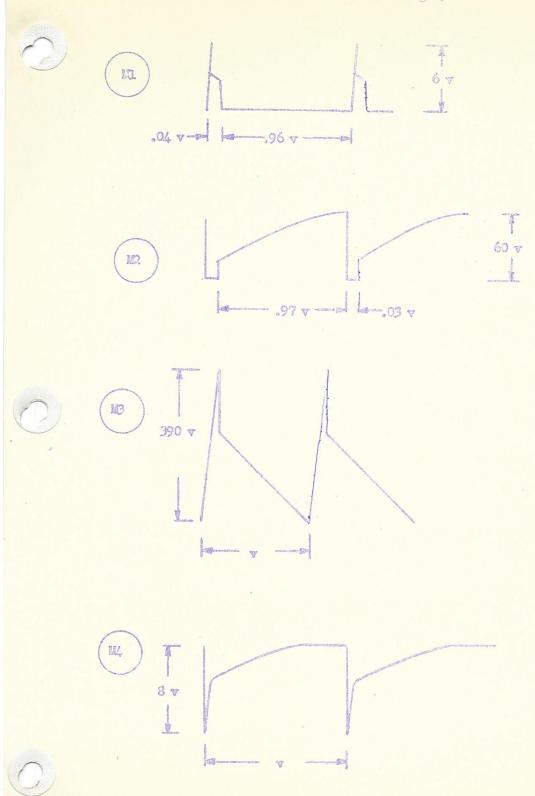


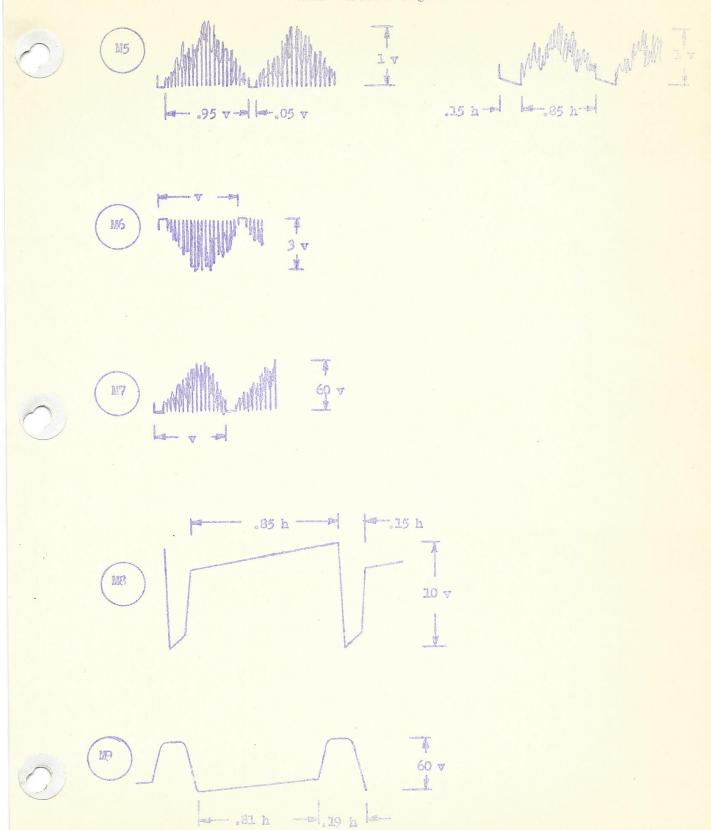


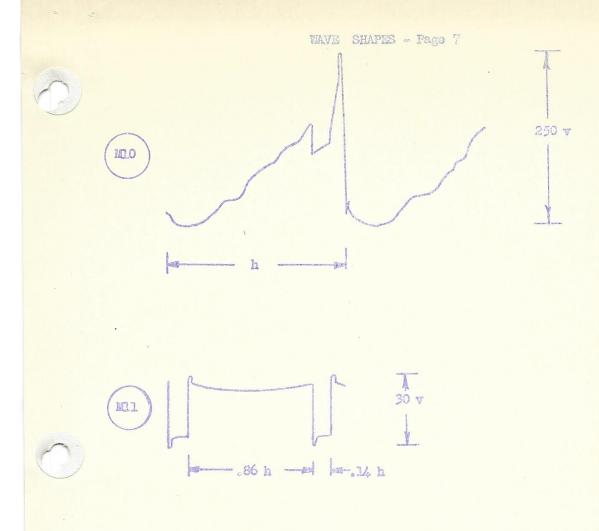


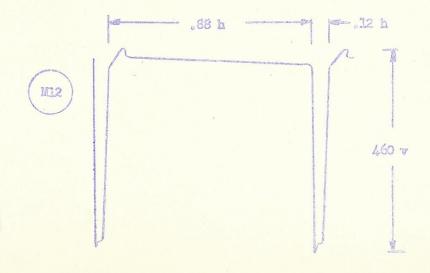












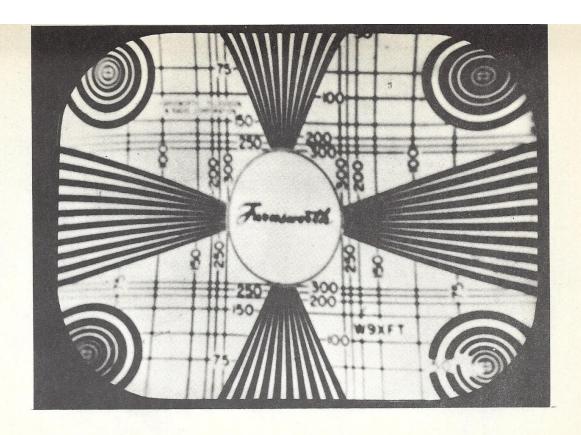
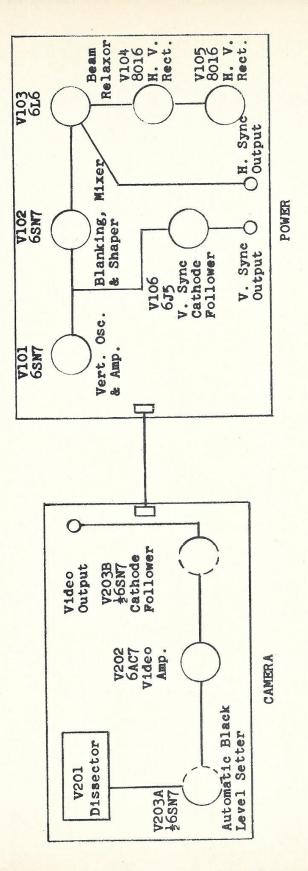


FIGURE I



FIGURE 2

FIGURE 3





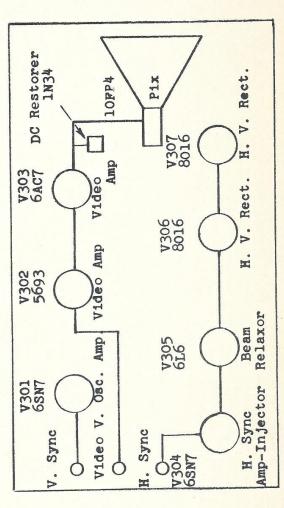
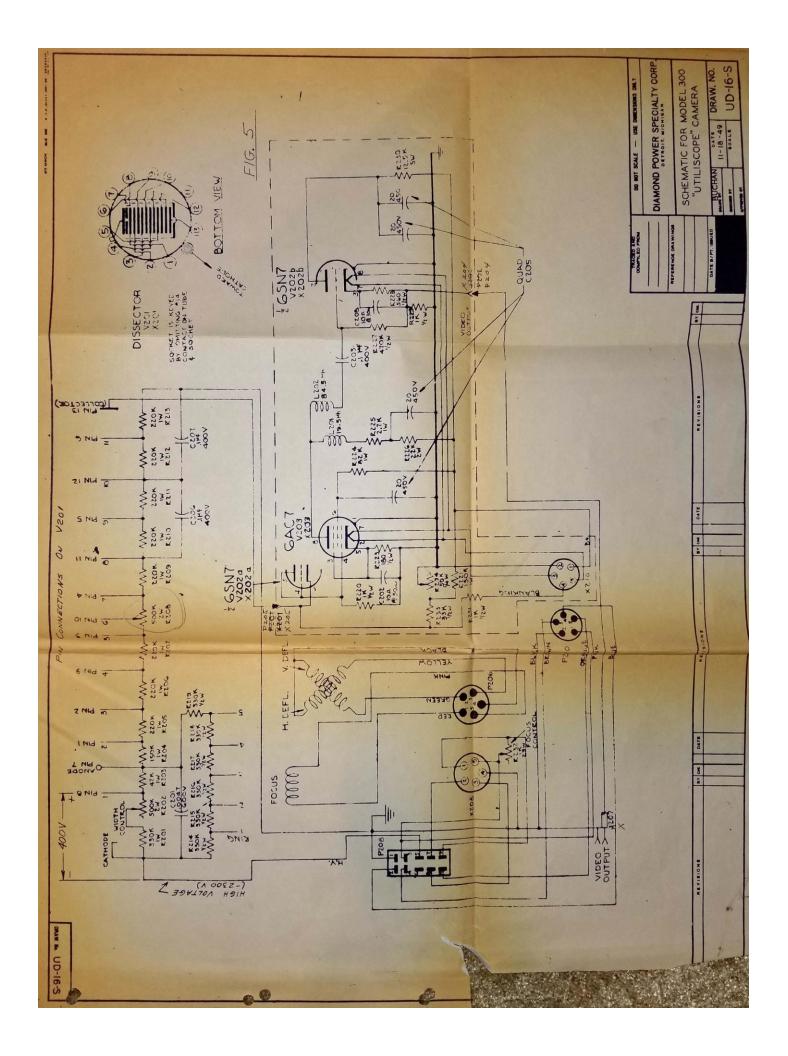
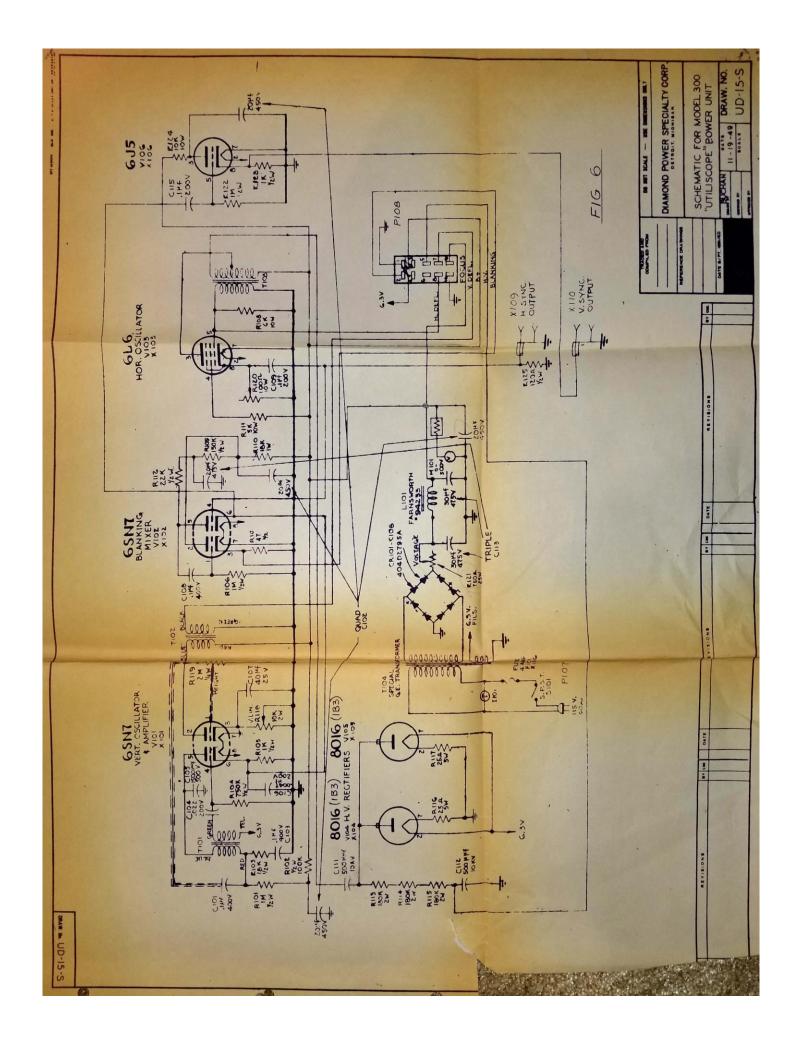


Figure 4





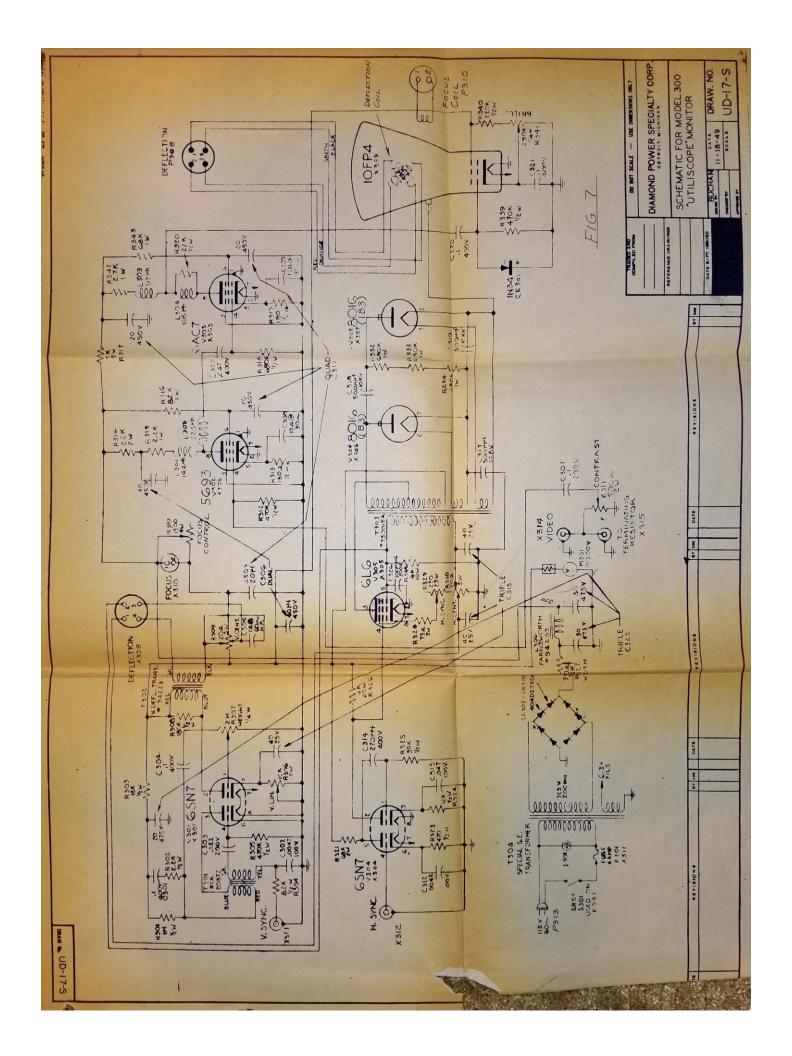
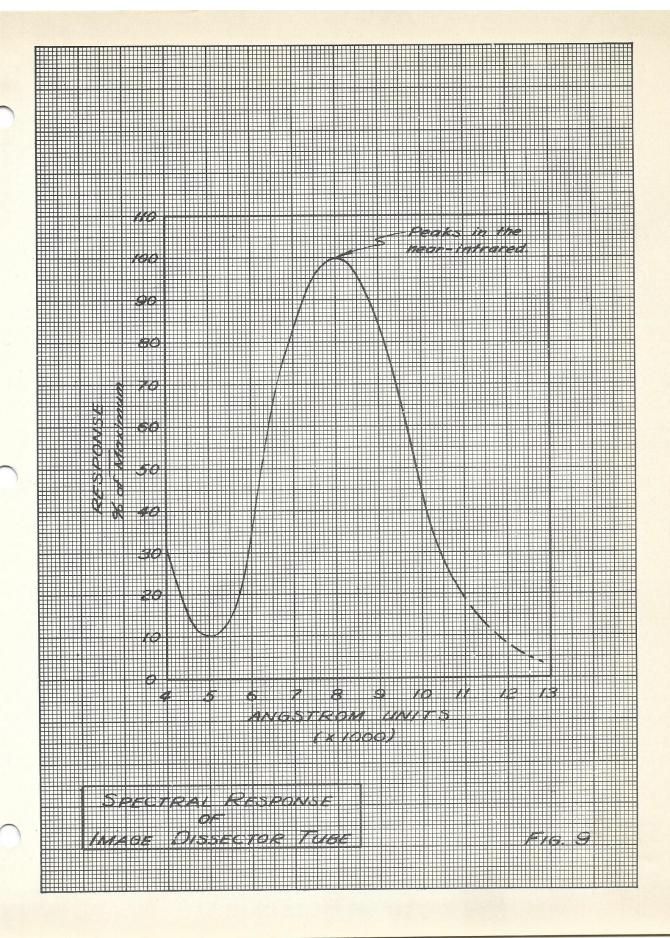
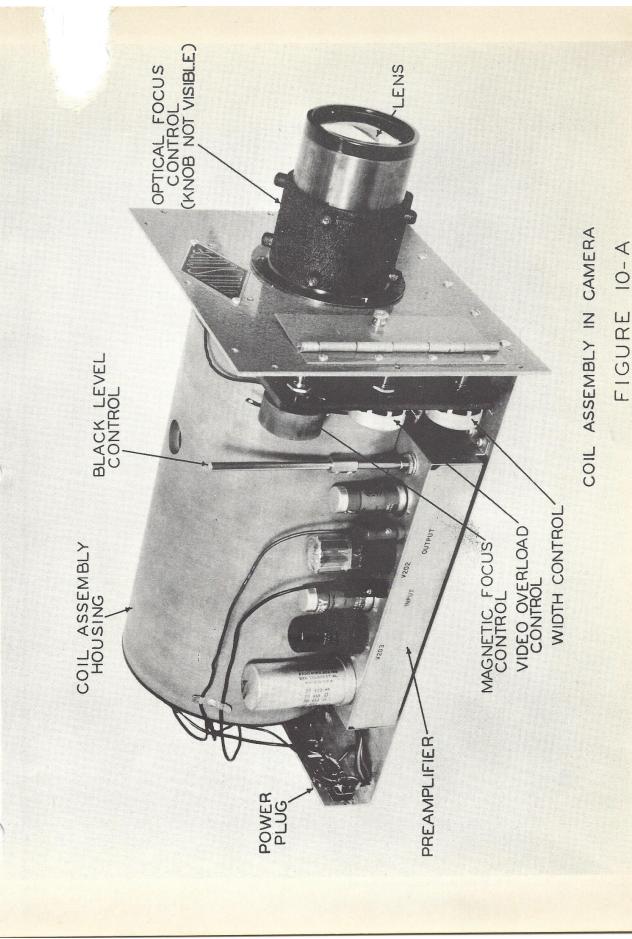
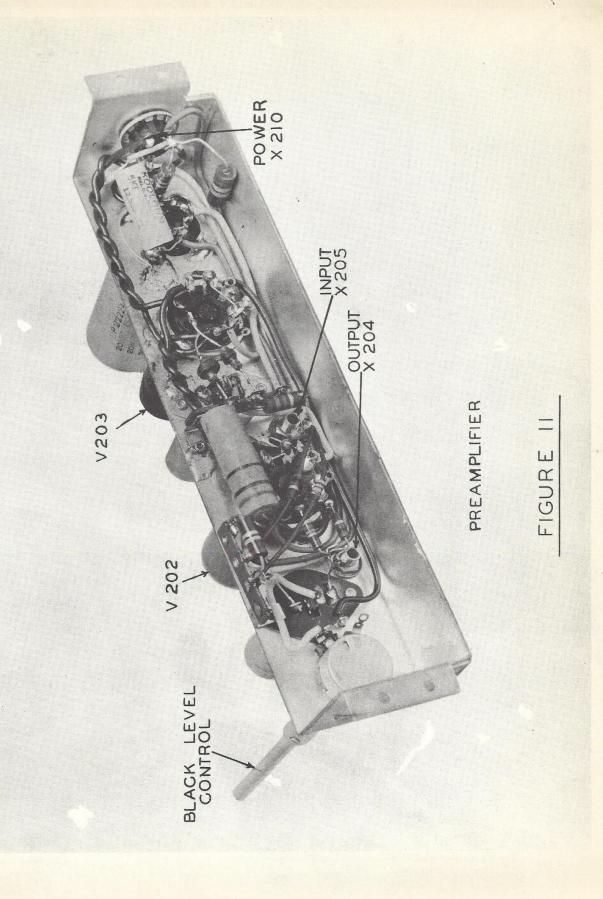
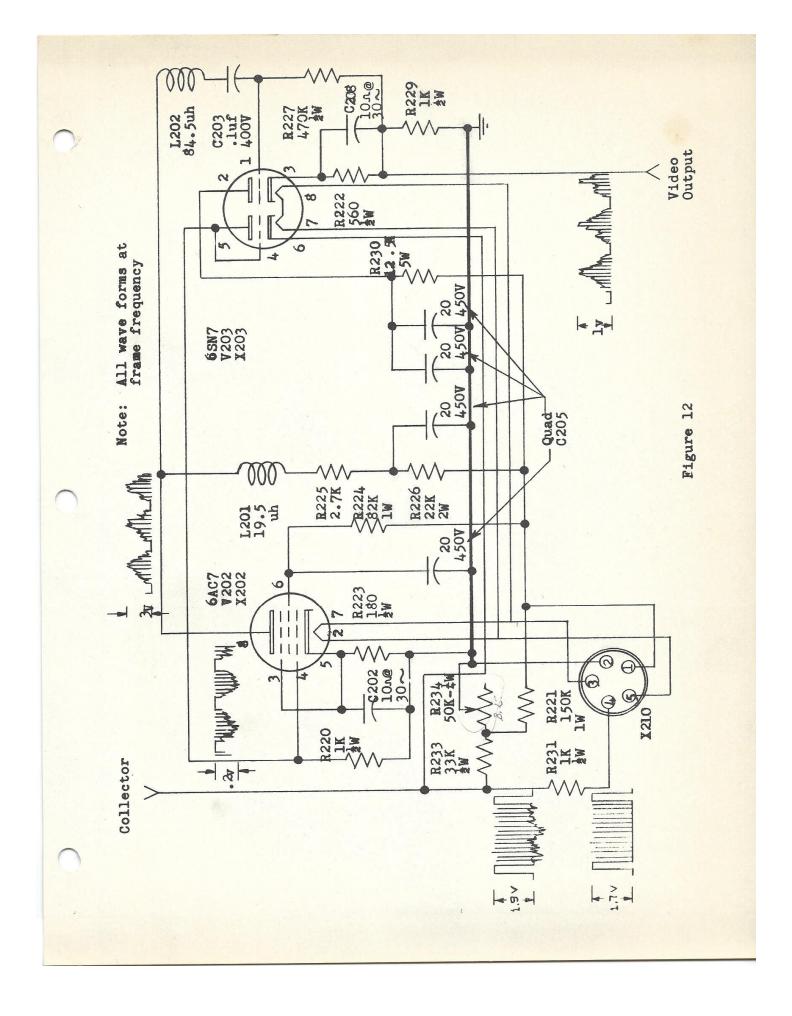


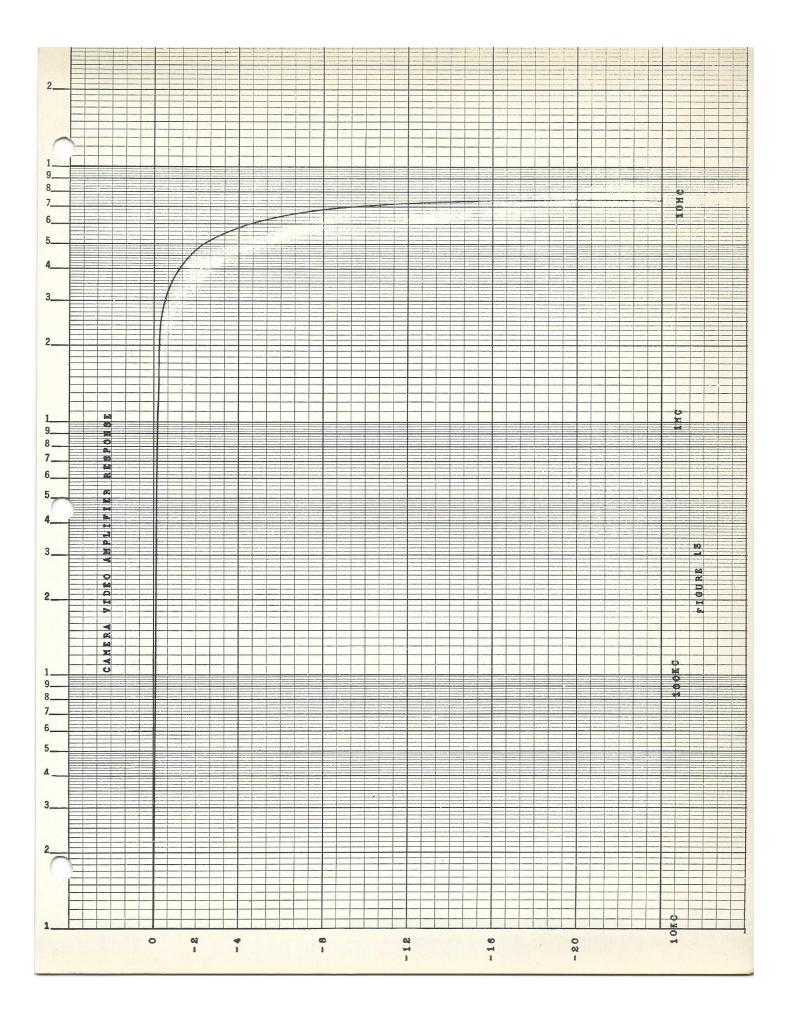
FIGURE 8

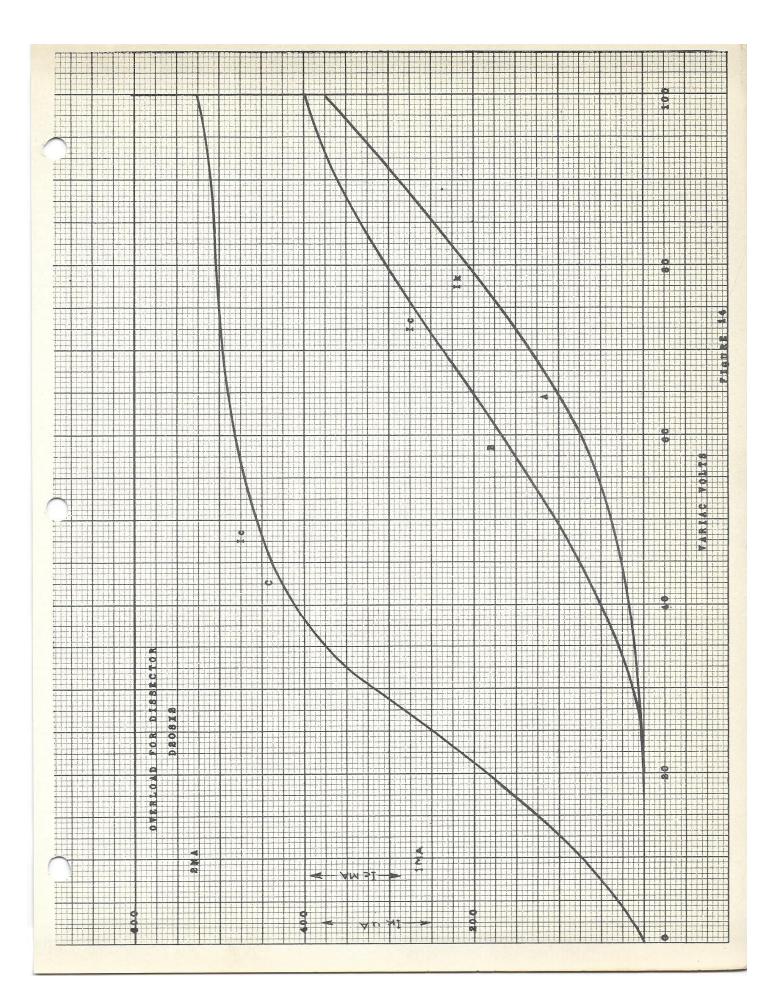












POWER UNIT

FIGURE 15

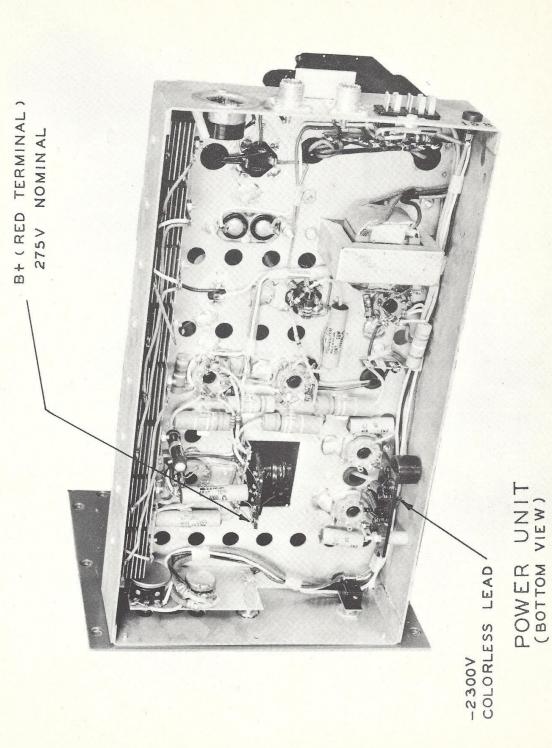
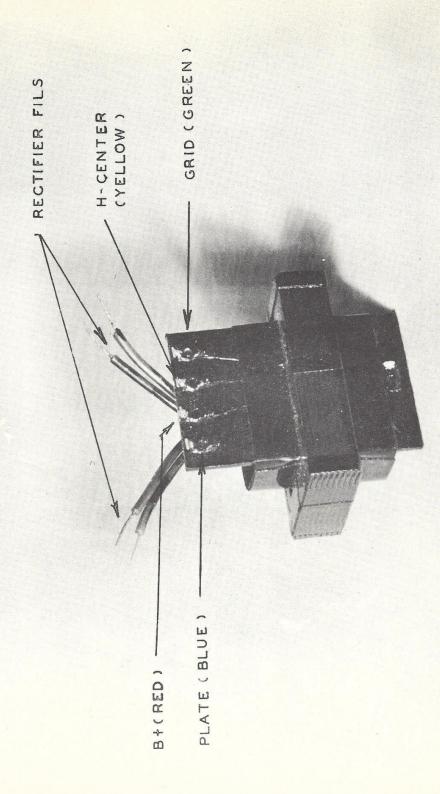


FIGURE 16

H-DEFLECTION TRANSFORMER (POWER UNIT) YELLOW (GROUND) BLUE CPLATE) GREEN (GRID)-(8+) RED

FIGURE 17-A



H - DEFLECTION TRANSFORMER (MONITOR)

FIGURE 17 - B

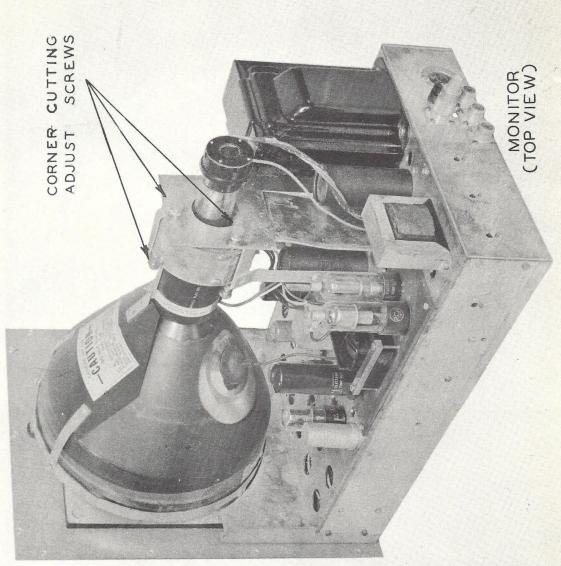
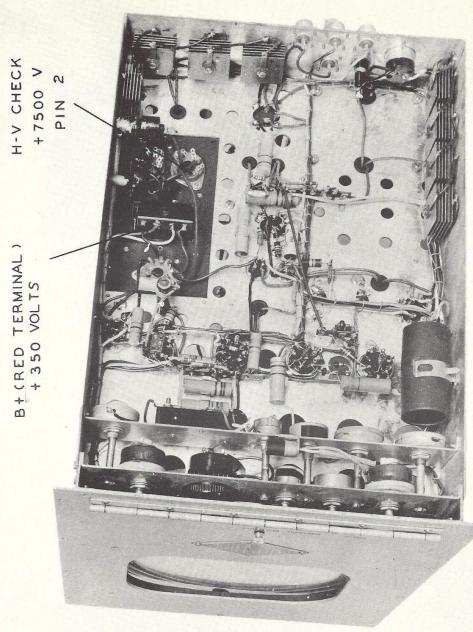


FIGURE 18

MONITOR (BOTTOM VIEW)



B+(RED TERMINAL) +350 VOLTS

